

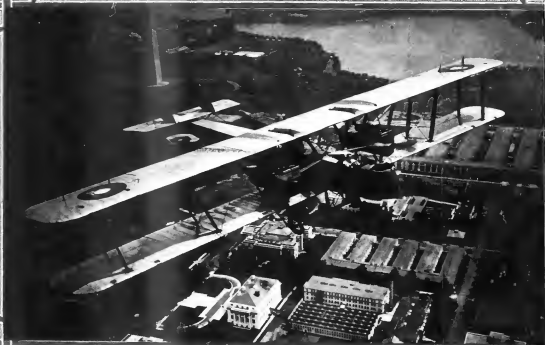
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AVIATION AND AERONAUTICAL ENGINEERING



Martin Bomber in Flight Over the Capital

VOLUME VII
Number 3

SPECIAL FEATURES

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SEPTEMBER 1, 1939

AVIATION AND AERONAUTICAL ENGINEERING

VOL. VII. NO. 3

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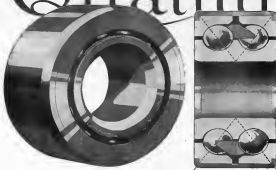
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AVIATION AND AERONAUTICAL ENGINEERING

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BUSINESS MANAGER

Vol. VII

September 1, 1919

No. 1

THE International Airplane Race and Handicap Contest organized by the American Flying Club, which ended just when AVIATION AND AERONAUTICAL ENGINEERING was going to press, afforded the American public the most important aeromedical demonstration ever given. The number of contestants and the types of airplanes entered made of this race the most important event of its kind in date, but beside this purely spectacular element an important innovation was furnished by the handicap formula which constitutes the first attempt to find a scientific expression for measuring the efficiency of airplanes belonging to a wide variety of types.

Owing to the fact that official figures on the outcome of the race are not available at the time of going to press discussion of its technical aspects has to be reserved; nevertheless the outstanding fact is that out of fifty-three actual starters, thirty-two, that is, over 60 per cent, finished the race within the set time limit. Of those eliminated by accidents four machines were totally crashed, but the remaining ships suffered only minor injuries which do not impair their future serviceability and—what is perhaps the most valuable lesson of the whole contest—only three airplanes were eliminated by engine trouble. This is truly a remarkable percentage if one considers that the race was run under most harassing weather conditions and that the control surfaces were in many cases unfavorably damaged with regard to the prevailing winds and of restricted area.

The New York-Toronto race was in particular a brilliant vindication of the Liberty engine, which propelled most of the big ships, although other engines showed up equally well, so that, altogether it may be said that American airplane engines have reached a point of perfection where they are second to none.

Likewise, the competing airplanes, virtually all of American design and manufacture, put up performances which justify the greatest pride and performance in the ability of our engineers and constructors.

The American Flying Club, as the organizer, and the Air Service, whose cooperation assured the success of the race, deserve the most sincere congratulations of the aircraft industry for having given such a magnificent object lesson of the potentiality of aviation.

Gyroscopic Effects of the Propeller

A good deal of controversy has been carried on with regard to the gyroscopic effects of the propeller. The gyroscopic forces have a bearing not only on the controllability of the plane, but also on propeller stresses, and on propeller bearing stresses.

Some designers have used as their criterion extremely rapidly rapid turns, and imposed excessive gyroscopic forces on their designs. Others have been inclined to neglect all consideration of these effects.

A simple method of considering the problem, which would nevertheless coordinate it with the general structural strength of the airplane, is to consider the airplane at the moment when it is banking out from a dive, at which time the dynamic forces are a maximum. Assuming the velocity to be known at such a point—and it will be very little below the landing speed of the airplane—a simple dynamical equation will give the rate of turn. And this rate of turn will furnish a very sound basis for computing the gyroscopic effects.

Inversion of Control Surfaces

In a recently published text-book of elementary aerodynamics, there occur the following lines: "In case of a very steep or vertical bank, the functions of rudder and elevators are completely reversed: the rudder, being then in a horizontal position, will be used to bring the nose of the machine up or down; the elevators being vertical serve to make the machine turn round." In connection with steep banks, the terms used for the rudder are top rudder and bottom rudder, irrespective of the fact that in either case it may be right or left rudder. For instance, if the machine is banked so that the right wing is down, then bottom rudder, in this case, would be equivalent to right rudder; but if the case is reversed, that is, if the machine is banked with the left wing down, then bottom rudder would mean left rudder."

Now this is a perfectly correct statement of the case, and, what is more, the terminology is very wisely adopted. Everywhere we read of reversed action, or of inversion of control surfaces.

And yet in reality there never is reversed action, and the terminology is unnecessarily confusing.

The difficulty arises from the fact that the earth and the vertical are considered as points of reference for the motion of the airplane, instead of the much more logical system of three axes at right angles to each other, passing through the center of gravity and rigidly fixed to the plane.

With such axes held in mind, the elevator as a steep or vertical bank is still performing its normal function of pitching the plane up and down about the aircraft's axis; the rudder is still performing its normal function of turning the plane to left or right about an axis in the plane perpendicular to the other two and longitudinal axis. Consequently there is no need for inversion of terminology.

aligned in juxtaposition in the 180 deg. by four-cylinder Mercedes engine, but with an additional two cylinders. It is not believed that many of these engines were used, as very few were captured, and during the latter part of the war they were considered obsolete.

The inertia balance of this type is easily obtained by referring to the curves given for the four-cylinder engine. By placing two resultant curves 90 deg. apart, thus being the relation of the crank arms, it will be found that the algebraic sum of their values at any point is zero. In reference to the transverse plane, the engine is therefore balanced in respect to inertia. The result looking angles show the longitudinal axis are present, however, as in any four-cylinder arrangement, but out of phase with each other by 90 deg.

A sixteen-cylinder Daimler engine was constructed by placing two eight-cylinder blocks vertically side by side on one

axial frame, the two axles being mounted on the engine as mounted in a fuselage. These vibrations are generally considered quite objectionable.

Suppose one firing is depressed with by decreasing the angle of V to 75 deg. The unbalanced component along the horizontal is somewhat diminished, but not to the extent of that introduced in the vertical plane. Neglecting up the cylinder heads obviously leaves the horizontal component of inertia so that at 80 deg. we find the component the same in any one direction, and therefore the unbalanced when considered in all directions. The Packard Co. have very recently brought out an engine of this type which, considered from the standpoint of unbalanced inertia, is a notable arrangement. The first Liberty engine had eight cylinders, with 85 deg. as the included angle of V. Although the horizontal component of inertia of this type is still further decreased, the vertical component becomes as large as the horizontal in the 90 deg. Vee type.



FIG. 2. POLAR DIAGRAM OF UNBALANCED INERTIA FORCES IN EIGHT-CYLINDER V-TYPE.

crankshaft. Since two crankshafts were employed the inertia balance of either row of cylinders was not altered. This engine was duplicated in this country and known as the King-Bombardier. The principal advantage of this arrangement is obtaining a suitable space between the two rows of cylinders as which to mount a cooling fan.

Eight-Cylinder Four-Type Engines

The eight-cylinder Vee type engine is virtually two four-cylinder in line engines operating on a single crankshaft. The angle at which these two banks of cylinders are placed on the crankshaft in respect to one another is influenced by various factors in design. Low level resistance in the airplane is desirable, therefore the cylinders can be arranged so that the fuselage loading which induces them will have a small vertical area. From intervals of explosion in advantage, but can be disposed with without detrimental effects if the gain in low level resistance warrants it.

The most common, or we may say conventional, angle of Vee for eight-cylinder engines is 90 deg. This arrangement gives even intervals of explosion, that is, explosions every 90 deg. of crank movement. It also leaves additional room between the cylinder heads in which to mount carburetors and manifolds into ready. The Common CX and the Hispano-Suiza engines are representative of many well-known cases constructed in this manner.

An odd bank of four cylinders has its respective unbalanced inertia, it is interesting to note the effects in the unbalanced inertia of the engine. In the English engine, the V-type, and a French engine, the Lorraine-Dietrich, are of this type. By referring to the diagram it will be readily seen, from EAC represents the unbalanced component, that the unbalanced inertia forces are greater in the horizontal than in the 90 deg. Vee type.

Consider first the conventional 90 deg. Vee engine. The horizontal line, shown on Fig. 3, signifies that these forces are effectively balanced in the horizontal plane. The diagram represents large magnitudes. The vibratory effects of these unbalanced



FIG. 3. POLAR DIAGRAM OF UNBALANCED INERTIA FORCES IN TWELVE-CYLINDER V-TYPE.

therefore looking it to be caused by inducing beyond a 90 deg. angle where it is possible to reduce the total resistance perceptibly as a result of the narrower angle.

Random-Cylinder V-Type

The best known states-of-the-art "V" type engine is the Model H Daimler, having two banks of eight cylinders with 45 deg. as the included angle. The length of this engine represents prohibitive dimensions for use in an airplane. It should be as far as for dirigibles. Since each bank of eight cylinders are in balance, it follows that the same is true for both.

Twelve-Cylinder W-Type Engines

The addition of a third bank of four cylinders gives a twelve-cylinder engine of approximately the same overall length as would one having four or eight cylinders. This is advantageous from the plane design standpoint, and the weight per horsepower should undoubtedly be less than a number of other twelve-cylinder types, but there are various objections to this arrangement, namely, added head resistance and poor inertia balance. On Fig. 4 are shown unbalanced inertia polar diagrams for some of these types in direct comparison with that of a 90 deg. Vee eight-cylinder engine of the same cylinder size.

Arranging the banks of four cylinders 90 deg. apart in each Vee gives even intervals of explosion and presents a fairly compact design. An English engine, the V-type, and a French engine, the Lorraine-Dietrich, are of this type. By referring to the diagram it will be readily seen, from EAC represents the unbalanced component, that the unbalanced inertia forces are greater in the horizontal than in the 90 deg. Vee type. This type of engine undoubtedly has numerous various mechanical advantages.

An experimental French engine, the Adolphe, is virtually a

conventional 90 deg. Vee with an additional bank of four cylinders operating vertically downward. FAD on the diagram signifies that, while the horizontal component is equal to the 90 deg. Vee angle, there has been introduced a vertical component of greater magnitude than that of a 90 deg. Vee engine. This is equally the vertical unbalanced component of the lower four cylinders, therefore we have in this arrangement the combined unbalanced inertia of two well-known engines.

Disposing the three banks of four cylinders were evenly spaced, that is, 120 deg. apart. Reversing the direction of one four-cylinder unbalanced component from the first arrangement described by changing the position of one set of cylinders from A to D produces a vertical unbalanced component as great as the horizontal. The polar diagram, shown on ECD, is a circle. It is evident that the inertia forces must be balanced in twelve cylinders engine composed of three rows of four and unbalanced components are introduced in excess of corresponding eight cylinder Vee types.

Three-Cylinder Engines

One of the earlier airplane engines constructed by Anzani had three cylinders arranged 120 deg. with 72 deg. as included angle. Four of these 120 deg. in the lower cylinders were probably the reason for this peculiar disposition. The engine only developed about 35 hp. and was poorly balanced for service. The interest is mainly historic as it preceded the first heavier than air craft in which the English Channel. Later Anzani built V type in which the cylinders were located 120 deg. apart. The inertia balance of this type will be found under the treatment of radial engines.

Three cylinders, arranged in line and operating three crankshaft 120 deg. apart, are in perfect inertia balance, but owing to their unbalanced lines of action being unbalanced, there is introduced a rocking couple. This can only be eliminated by an additional three cylinders in line producing the crank arrangement is symmetrical.

Five-Cylinder Engines

It is quite generally known that there are no resultant unbalanced inertia forces in the conventional six cylinder engine, but in order to make this point clear Fig. 5 is given. V-type engines, but in reference to the diagram it will be readily seen, from EAC represents the unbalanced component, that the unbalanced inertia forces are greater in the horizontal than in the 90 deg. Vee type.

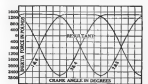


FIG. 4. INERTIA FORCES IN SIX-CYLINDER ENGINES.

Rate as rule of six cylinders is in perfect inertia balance, it follows that odd engines which are an odd number of cylinders at their arrangement, are also in perfect inertia balance. This applies particularly to twelve cylinder engines, such as the Common Model H, Daimler-Benz, Lorraine-Dietrich, and many others. Eighteen cylinders W-type, composed of three rows of six, are not uncommon, but should be in favor for reasons of higher power output. A Siemens engine is probably the best known of this type.

Radial Engines

The radial engine type, having a fan-like shape arrangement of cylinders and a revolving crankshaft, presents an interesting problem of inertia balance. The diagrams represent the resultant inertia forces of various numbers of cylinders

arranged radially. The inertia force values for all cylinders were obtained by use of the formula at the proper crank angle, laid off about each cylinder arm in respect to magnitude and direction and summed.



FIG. 5. DIAGRAM OF RESULTANT INERTIA FORCES IN RADIAL ENGINES.

It is interesting to note that in all but one case, the resultant diagram is practically a circle. As any instant the resultant unbalanced inertia is in the direction of the crankshaft from the cylinder arm, therefore it moves about under the crank speed having the same direction as the inertia force of any one cylinder when it is greatest; namely, at its outermost position period. Since the resultant force for the various odd numbers of radial engine cylinders is practically constant during one revolution, a direct comparison may be made with the inertia force of one cylinder with which it corresponds in direction. This will be taken at its outermost position, that is, when the piston is at the top of its stroke and furthest away from the crank arm. The radius of the dotted circle in the center is a measure of magnitude of the inertia force of one cylinder at 0 crank angle.

The resultant primary and secondary inertia forces are not necessarily considered individually. In all structures it is the resultant of the primary inertia forces which governs at crank speed and at any instant is in the direction of the inertia force of one cylinder whose piston is at its outermost position. Some designers only attempt to balance the resultant of the primary forces, neglecting the secondary as these are generally considered as being of little importance. The secondary resultant is usually twice as great as the primary, but at twice crank speed.

The cylinders in one plane and evenly spaced about a single crank pin may be said to be in order to obtain equal intervals of firing. The diagram represents the disposition of cylinders which number three to eleven radially, the latter being the greatest number has been found possible to mount on a crankshaft without producing prohibitive overall dimensions from the standpoint of head resistance to the expansion. It is somewhat better to use odd numbers of cylinders located in two planes and operating about a two-crank crankshaft, which has crank pins 180 deg. apart. The inertia balance of this type follows the treatment for the single plane of cylinders.

As previously stated, a direct comparison can be made between the resultant unbalanced inertia of any odd number of cylinders in one plane and the same number of one cylinder in its outer position. The diagram shows this clearly and may be used to obtain the rates, but more accuracy will result if inertia is made in two planes. The inertia force of one cylinder is subject to slight variation with different crank throw and connecting rod lengths. The ratio $\frac{r}{l}$ in this case has been taken at $\frac{1}{3}$ which approximates most airplane engine practice. The value of the resultant primary and secondary inertia is

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Part III.—Experimental Aeronautical Engineering

By Alexander Klemin

Technical Editor, Aviation and Aeronautical Engineering, Consulting Engineer, Aerial Mail Service, Consulting Aeronautical Engineer

Section 8.—Wind Tunnel Experimentation

Recent Progress in Aeronautical Laboratories

In Part I, Section 1 of this course (Aviation and Aeronautical Engineering, August 1, 1934) under the heading of "Modern Aeronautical Laboratories" a fairly complete account was given of the aeronautical laboratories then in existence. Progress since that date has been rather in new than in development, the general characteristics of both tunnel, balance and gage apparatus remaining substantially the same. Propeller wind tunnels which have developed will not be included in this account, nor the methods developed in the investigation of stability.

National Physical Laboratory (England)

The first efficient N. P. L. tunnel was of 3 ft. x 3 ft. section. The following table indicates the changes of tunnel over the years.

	1914	1915	1916	1917	1918	1919	1920	1921	1922	1923	1924	1925	1926	1927	1928	1929	1930	1931	1932	1933	1934	1935	1936	1937	1938	1939	1940	1941	1942	1943	1944	1945	1946	1947	1948	1949	1950	1951	1952	1953	1954	1955	1956	1957	1958	1959	1960	1961	1962	1963	1964	1965	1966	1967	1968	1969	1970	1971	1972	1973	1974	1975	1976	1977	1978	1979	1980	1981	1982	1983	1984	1985	1986	1987	1988	1989	1990	1991	1992	1993	1994	1995	1996	1997	1998	1999	2000	2001	2002	2003	2004	2005	2006	2007	2008	2009	2010	2011	2012	2013	2014	2015	2016	2017	2018	2019	2020	2021	2022	2023	2024	2025	2026	2027	2028	2029	2030	2031	2032	2033	2034	2035	2036	2037	2038	2039	2040	2041	2042	2043	2044	2045	2046	2047	2048	2049	2050	2051	2052	2053	2054	2055	2056	2057	2058	2059	2060	2061	2062	2063	2064	2065	2066	2067	2068	2069	2070	2071	2072	2073	2074	2075	2076	2077	2078	2079	2080	2081	2082	2083	2084	2085	2086	2087	2088	2089	2090	2091	2092	2093	2094	2095	2096	2097	2098	2099	2100	2101	2102	2103	2104	2105	2106	2107	2108	2109	2110	2111	2112	2113	2114	2115	2116	2117	2118	2119	2120	2121	2122	2123	2124	2125	2126	2127	2128	2129	2130	2131	2132	2133	2134	2135	2136	2137	2138	2139	2140	2141	2142	2143	2144	2145	2146	2147	2148	2149	2150	2151	2152	2153	2154	2155	2156	2157	2158	2159	2160	2161	2162	2163	2164	2165	2166	2167	2168	2169	2170	2171	2172	2173	2174	2175	2176	2177	2178	2179	2180	2181	2182	2183	2184	2185	2186	2187	2188	2189	2190	2191	2192	2193	2194	2195	2196	2197	2198	2199	2200	2201	2202	2203	2204	2205	2206	2207	2208	2209	2210	2211	2212	2213	2214	2215	2216	2217	2218	2219	2220	2221	2222	2223	2224	2225	2226	2227	2228	2229	2230	2231	2232	2233	2234	2235	2236	2237	2238	2239	2240	2241	2242	2243	2244	2245	2246	2247	2248	2249	2250	2251	2252	2253	2254	2255	2256	2257	2258	2259	2260	2261	2262	2263	2264	2265	2266	2267	2268	2269	2270	2271	2272	2273	2274	2275	2276	2277	2278	2279	2280	2281	2282	2283	2284	2285	2286	2287	2288	2289	2290	2291	2292	2293	2294	2295	2296	2297	2298	2299	2300	2301	2302	2303	2304	2305	2306	2307	2308	2309	2310	2311	2312	2313	2314	2315	2316	2317	2318	2319	2320	2321	2322	2323	2324	2325	2326	2327	2328	2329	2330	2331	2332	2333	2334	2335	2336	2337	2338	2339	2340	2341	2342	2343	2344	2345	2346	2347	2348	2349	2350	2351	2352	2353	2354	2355	2356	2357	2358	2359	2360	2361	2362	2363	2364	2365	2366	2367	2368	2369	2370	2371	2372	2373	2374	2375	2376	2377	2378	2379	2380	2381	2382	2383	2384	2385	2386	2387	2388	2389	2390	2391	2392	2393	2394	2395	2396	2397	2398	2399	2400	2401	2402	2403	2404	2405	2406	2407	2408	2409	2410	2411	2412	2413	2414	2415	2416	2417	2418	2419	2420	2421	2422	2423	2424	2425	2426	2427	2428	2429	2430	2431	2432	2433	2434	2435	2436	2437	2438	2439	2440	2441	2442	2443	2444	2445	2446	2447	2448	2449	2450	2451	2452	2453	2454	2455	2456	2457	2458	2459	2460	2461	2462	2463	2464	2465	2466	2467	2468	2469	2470	2471	2472	2473	2474	2475	2476	2477	2478	2479	2480	2481	2482	2483	2484	2485	2486	2487	2488	2489	2490	2491	2492	2493	2494	2495	2496	2497	2498	2499	2500	2501	2502	2503	2504	2505	2506	2507	2508	2509	2510	2511	2512	2513	2514	2515	2516	2517	2518	2519	2520	2521	2522	2523	2524	2525	2526	2527	2528	2529	2530	2531	2532	2533	2534	2535	2536	2537	2538	2539	2540	2541	2542	2543	2544	2545	2546	2547	2548	2549	2550	2551	2552	2553	2554	2555	2556	2557	2558	2559	2560	2561	2562	2563	2564	2565	2566	2567	2568	2569	2570	2571	2572	2573	2574	2575	2576	2577	2578	2579	2580	2581	2582	2583	2584	2585	2586	2587	2588	2589	2590	2591	2592	2593	2594	2595	2596	2597	2598	2599	2600	2601	2602	2603	2604	2605	2606	2607	2608	2609	2610	2611	2612	2613	2614	2615	2616	2617	2618	2619	2620	2621	2622	2623	2624	2625	2626	2627	2628	2629	2630	2631	2632	2633	2634	2635	2636	2637	2638	2639	2640	2641	2642	2643	2644	2645	2646	2647	2648	2649	2650	2651	2652	2653	2654	2655	2656	2657	2658	2659	2660	2661	2662	2663	2664	2665	2666	2667	2668	2669	2670	2671	2672	2673	2674	2675	2676	2677	2678	2679	2680	2681	2682	2683	2684	2685	2686	2687	2688	2689	2690	2691	2692	2693	2694	2695	2696	2697	2698	2699	2700	2701	2702	2703	2704	2705	2706	2707	2708	2709	2710	2711	2712	2713	2714	2715	2716	2717	2718	2719	2720	2721	2722	2723	2724	2725	2726	2727	2728	2729	2730	2731	2732	2733	2734	2735	2736	2737	2738	2739	2740	2741	2742	2743	2744	2745	2746	2747	2748	2749	2750	2751	2752	2753	2754	2755	2756	2757	2758	2759	2760	2761	2762	2763	2764	2765	2766	2767	2768	2769	2770	2771	2772	2773	2774	2775	2776	2777	2778	2779	2780	2781	2782	2783	2784	2785	2786	2787	2788	2789	2790	2791	2792	2793	2794	2795	2796	2797	2798	2799	2800	2801	2802	2803	2804	2805	2806	2807	2808	2809	2810	2811	2812	2813	2814	2815	2816	2817	2818	2819	2820	2821	2822	2823	2824	2825	2826	2827	2828	2829	2830	2831	2832	2833	2834	2835	2836	2837	2838	2839	2840	2841	2842	2843	2844	2845	2846	2847	2848	2849	2850	2851	2852	2853	2854	2855	2856	2857	2858	2859	2860	2861	2862	2863	2864	2865	2866	2867	2868	2869	2870	2871	2872	2873	2874	2875	2876	2877	2878	2879	2880	2881	2882	2883	2884	2885	2886	2887	2888	2889	2890	2891	2892	2893	2894	2895	2896	2897	2898	2899	2900	2901	2902	2903	2904	2905	2906	2907	2908	2909	2910	2911	2912	2913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detailed description of the balance the reader is referred to original reports.

Wind Tunnel Velocity Instruments

Apart from the balance, wind tunnel representation requires a large number of subsidiary instruments, such as anemometers, speed devices for testing air surface in the presence of surface, and many other pieces of apparatus which the operator has to derive and build for himself. The velocity measuring instruments are more or less standardized and some of them are purchasable. These include:

Pitot Tube

A full description of this was given in Part I, Section 2. The Pitot tube is indispensable in the initial calibration of the tunnel, and in exploring the cross-section of the canal for regularity of flow, but it is not suitable for measuring the velocity of flow of the tunnel during representation, as soon



FIG. 3. APPROXIMATE BALANCE

the smallest Pitot will create a disturbance in the air flow. It is therefore replaced by a side plate as shown in Fig. 4.

Side Pressure Plate

The theory of the side pressure plate is very simple. If p = pressure at any point in a stream, v = velocity at any point in a stream, d = density at any point in a stream, and p_0 = pressure where v is zero, then by Bernoulli's theorem:

$$p + \frac{\rho v^2}{2} = p_0$$

As an open-air wind-tunnel of the N. P. L. or Eiffel type the flow enters the tunnel which is therefore at lower section. The air is decelerated by the flow through a screen into the building at rest and, when it returns at low velocity, to the other end to pass again into the tunnel.

At a point in the room the total pressure, which would be transmitted by a pressure input tube would be $p_0 + \frac{\rho v^2}{2}$.

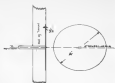
The quantity $\frac{\rho v^2}{2}$ is so small, however, owing to the low return velocity in a large room, that it is possible to write

$$p_0 = p + \frac{\rho v^2}{2}$$

If therefore a hole in the side of the tunnel is connected with one end of a liquid manometer, and the other end of the manometer is left open to the room, the gauge reading will be

$$p - p_0 = p - p + \frac{\rho v^2}{2}$$

Steadily speaking: $p = p + \frac{\rho v^2}{2} + p_0$, where p_0 is a measure of the friction losses. The error due to the side plate is of the order of 3 per cent. It is therefore necessary to calibrate the



side plate and its manometer against the standard Pitot tube and its manometer.

The side plate shown in Fig. 4 consists of a thin brass disk about 3 in. in diameter, set flush in the wall of the tunnel. The disk is flat and lightly polished. Near its center, the hole 6/32 in. in diameter is drilled. Two holes are counter-bored with a brass tube soldered to the back of the plate and projecting through the side of the channel. Rubber tubing is used to transmit the static pressure from the small holes to one end of a manometer.

The pressure transmitted by the side plate has been found to respond very quickly to changes in velocity, and the method



FIG. 5. PITOT TUBE

is even more sensitive than the Pitot tube. Naturally this pressure is no smaller than that of the Pitot used for its calibration.

The pressure difference transmitted by the side plate is read on an uncalibrated side manometer on the Kroll principle. Both the side plate and this side manometer require calibration against a standard. For convenience, the side plate and its manometer are calibrated together against a standard Pitot tube and a standard manometer. The procedure in such a calibration is obvious.

The Kroll Manometer

The ordinary U-tube manometer filled with water, gasoline, alcohol, or other light liquid, shows a head of less than 1 in. for ordinary velocities, and it is impracticable to read the movement of the meniscus. An inverted manometer such as the Kroll gives a much larger displacement for a given head. This manometer is shown in Fig. 5. One leg of the U-tube is an inverted glass tube and the other is a receiving bottle whose surface is once 400 times the section of the tube. Hence, at

liquid rises in the glass tube, the depression in the reservoir is proportional.

As shown in Fig. 6, the reservoir R is mounted in a hinged plate with leveling screws. By means of the latter the liquid in the tube is brought to the zero of the scale at the beginning of a test, thus making a zero correction unnecessary. The glass tube T is likewise mounted on a brass plate provided at the top edge E , and adjusted to pitch by the screw S . To the brass plate are attached permanently two small "machinist" levels L , and L , set at 3 deg and 6 deg in the axis of the tube. For low velocity the 3 deg inclination is used. Displacement of the liquid in the tube T is read on a scale graduated to half a millimeter. The head is given by the formula:

Head of liquid = displacement in T x side of calibration. From experimental work at the Massachusetts Institute of Technology, the following conclusions were reached:

(1) The inclined type of liquid gauge is commonly employed in wind-tunnel work as not an indication of pressure.



FIG. 6. KROLL MANOMETER

(2) For constant results, the glass tubing used must be free from all slight flaws in the outer surface which might cause changes in capillarity throughout the bore.

(3) The tube must be uniform in diameter.

(4) The tube must be as large as it is possible to use and still get a good meniscus.

(5) For sloped at 3 deg inclination an internal diameter of 0.2 in. is suitable.

(6) The maximum pressures with such a gauge used as manometer are up to 4 to 40 in. per in. at about 1.5 per cent on velocity.

(7) The sloped gauge properly constructed is sensitive and very accurate.

(8) The sloped gauge may be used as an instrument of pressure when calibrated against a standard.

The Chertkov Gauge

The Chertkov gauge is shown in Figs. 7 and 8. The principle of the gauge is that of the inclined liquid U-tube, but, instead of giving the tube an actual slope and observing the change of level of the liquid, the Chertkov gauge is fitted with an electric level and manometer by which the gauge is tilted to balance the pressure difference in its two ends. By reading on the manometer the amount of tilt given, the head in inches of liquid is ascertained. By this means there is no motion of the liquid in the glass, and errors due to capillarity and viscosity are eliminated. Furthermore, the resolution of the surface of the glass has no effect.

The gauge consists of a glass U-tube mounted on a tilting frame F . The pressure to be measured is connected to the bottle A and C , which are in communication with each other through a horizontal tube bearing a third hole B at its center. The bottle A and C are the lower part of B is filled with water. The upper part of B is filled with water. The water in A and C is in communication with the water in B at the pressure of C . The water in A is led through a thin-walled tube through the bottom of B entering

into the outer air. An excess of pressure in A over the pressure in C will cause water to flow from A into B . A water bubble will then grow at D and expand into the air. The gauge can be used to measure the pressure in a gas or a liquid. The pressure in A and C are then balanced. To provide this the manometer is mounted on a tilting frame F , which gives it the angle edge E and is elevated by the screw S . The whole is controlled on a ball frame S fitted with three leveling screws L , a retaining spring R , and a scale S , on which may be read the full range of the screw S .

A manometer M , filled with cross-hatched, is mounted on the frame F and viewed at the bubble B . A small mirror on the opposite side illuminates the surface of the bubble. The screw S is fitted with a larger disk revolved into 300 parts. The screw has 30 threads to the inch. The gauge is sensitive to one-half of a division on the drum, and hence to a movement of the bubble of 1/1,000 in.

Before a measurement is taken the bubble B and C are

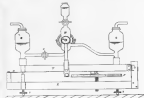


FIG. 7. CHERTKOV MANOMETER

opened to the air of the room and the frame tilted by moving the manometer until the top of the bubble B is brought tangent to the horizontal cross-wire of the manometer. This is the zero reading. The bubble B and C are then connected to the two parts of a Pitot tube and the frame tilted until the bubble is again on the cross-wire. The amount of tilt in then read on the manometer.

For the calculation of tilt it is then necessary to measure the distance between the centers of the bubble B and C and the distance from the bubble edge E to the bubble F . An error of 0.1 in. is either of these measurements is an error of 1 per cent in head or 0.5 per cent in velocity. There is no difficulty in getting these distances in the current head-tube of an inch. The error due to the tilt of the frame is not so important to detect any error in the pitch of the thread. The tube T is tapped with a standard Brown and Sharpe tap. The circular disk of the change in level of the surface of the liquid in A and C is given to 0.1 per cent.

Since the gauge is sensitive to less than 0.1 per cent for heads of more than 0.5 in., the measurement of velocity depends on the pressure of the Pitot tube. The latter is good to probably 0.10 per cent in velocity. However, the air current always has some fluctuation at high speeds so that in the end the velocity measurement is limited in precision by the fluctuation with which such fluctuations can be averaged. In a very steady current, such as in a wind tunnel, it is found that the error in obtaining velocity is less than 0.3 per cent. The average of a number of observations is, of course, better than this.

Change in density of the salt solution is 1/10 per cent for a change of 0.01 deg. F. at temperature. A temperature correction is obviously necessary.

References

Design and Use of Wind Tunnel, by J. S. Pennell, a paper before the Aeronautical Society of Great Britain. With a list of references. (See also) Experimental Aerodynamics, Massachusetts Collection, Vol. 42. Berlin Advisory Committee's Report 1918-1919.

The Trompenburg Pursuit Airplane

The Trompenburg pursuit airplane was built for the Netherlands Air Service by the Trompenburg Airplane and Automobile Manufacturing Co., of Amsterdam. It is the design of Henry Trompenburg, the well-known pre-war aviator. This machine is noteworthy not only as a Dutch sample of modern airplane construction but, also, an example of its performance, which is remarkably good if one considers the comparatively low powered engine employed. It is shown from the accompanying photographs that this performance is principally due

The motor section is fixed to the fuselage by means of four vertical streamlined struts, while the planes are braced inside the fuselage struts by one pair of vertical corrugated struts. Two oval side windows are let in the motor section to increase the pilot's visual range upward. No flaps, wingtips or ailerons are included in the wings; positive ailerons are fitted to both upper and lower planes.

The fuselage is really of rectangular cross-section, with slightly curved sides, and is apparently built up of four



QUARTER FRONT VIEW OF THE TROMPENBURG PURSUIT AIRPLANE

in the design of the whole airplane, incorporating careful streamlining of the fuselage, planes wing bracing and the use of winged wire for support struts.

Both upper and lower planes have a span of 8.10 m., and a chord of 1.41 m. Each plane of either right or left hand wing is of equal span, the upper planes being joined by a single section of 0.65 m. width, while the lower planes are attached to the lower fuselage longerons. This arrangement is distinctly advantageous from the production viewpoint because all planes are structurally identical, although, of course, they are not interchangeable since they are connected, thus owing to the position of the intercepting strut rods, etc.

longerons with either square bulkheads or wire braced cross struts ensuring stability. Information as to the detail is not furnished by the manufacturer.

The power plant consists of an air-cooled Gnome rotary engine, built by the manufacturer, which has a bore of 128 mm. and a stroke of 160 mm. and develops 130 hp. at from 1,100 to 1,500 r.p.m. Two machine guns are synchronized with the engine for firing through the propeller. The fuel capacity is 20 gal. the oil capacity 4 gal.

The machine has a high speed of 185 kmph. (115 mph.) and climbs 5,000 m. (16,400 ft.) in 2 min. and 3,000 m. (9,840 ft.) in 11 sec.

The main airship routes and times of travel on this scheme will be as follows: all voyages starting from London To New York, 3½ days; San Francisco, 5½; Cairo, 1½; Colombia, Orinoco, 4½; Porto, Antioquia, 1; Santos, East Africa, 3½; Cape Town, 3½; Rio de Janeiro, 1.

The British wireless system, to take advantage of the prevailing winds, will consist of two main lines direct and via London and the Azores to New York and thence to San Francisco. The London to Rio de Janeiro route will be by way of Lisbon and Sierra Leone.

The Marine Vickers have already announced a provisional fare of £240 per passenger in New York, and will retail at 3½ pence an ounce.

Pacific Coast Taxis

The Pacific Airline Co. of San Francisco, Cal., has established an aerial taxi service on the Pacific Coast. Two passenger planes, piloted by R. M. Spencer, former test pilot at McCook Field and Sam Parrell, former instructor at San Diego, are operated at present between San Francisco, Calif., where it is planned to install a fleet of ten passenger carrying planes within the next few months. The two planes now in use are of the Glenn Martin TT type with Curtiss OX-5, 200-horsepower.

Weekly travelers are to be relieved by small, non-regd airships maintained at much the same cost as a small taxi.

It would appear that the Vickers will be one of the members of the above establishment.

The Vickers passenger airships under development will be of 3,500,000 cu. ft. capacity, will be housed comfortably in a distance shed, and carry 4500 tons of passengers and mail. For a maximum of 4,500 miles at a speed of 60 m.p.h.

The Van Sicklen Chronometric Tachometer

By Frank J. Feely

There are many types of speed measuring devices, which operate upon nearly as many different principles. Some of these have been quite successfully used on automobile speedometers, but on account of the extreme conditions encountered in airplane operation, most of these instruments were not satisfactory, for this use. Extreme temperature variation, change in air density, vibration, and the existence of stray magnetic fields disturbed all but two types of instruments for satisfactory use on airplanes, namely, the chronometric and the centrifugal types.

Both of these are strictly mechanical in operation, the first measuring speed by time, and the second using the well known principle of centrifugal force which is used in a steam engine governor. The chronometric tachometer is introduced in article and registers speed every second or every other second,



FIG. 1. TACHOMETER WITH TOP PLATE AND FRONTING DIAL REMOVED

while the centrifugal is continuous with the time lag caused by the inertia of its spring parts. The chronometric tachometer has a uniform dial, and never de-conditions as evidenced by the fixing of its watch coil, an accuracy approached that of a watch. This accuracy is of a very high order, being greater than that of any other speed measuring device. The centrifugal tachometer has a fractional lag which causes it to register less on increasing speeds than on decreasing speeds. This difference in the spring centrifugal mechanism on the average is nearly 60 r.p.m. on increasing and decreasing speed. The chronometric tachometer does not have this fractional lag.

The general principle of all chronometric tachometers is the same. Speed is measured by time just as with the ordinary speedometer and stop watch. However, the wheel is performed automatically and in a shorter space of time than it is with an ordinary speedometer. In general, the instrument has a counting mechanism which is connected to the driven member automatically for a given period of time, usually one second. During this time, the counting mechanism makes a count of speed, and then it is disengaged from the drive mechanism, and allowed to return to zero position. An accumulating mechanism registers this speed and the pointer remains stationary while the counting mechanism is returned to zero.

The writer will restrict himself to the description of the Van Sicklen chronometric tachometer. Parts of this instrument are illustrated in Figs. 1 to 5, the assembled instrument in Fig. 1, but the dial is simply uniformly graduated from 0 to 3,000 r.p.m. for a complete rotation of the pointer. Fig. 1 shows the assembled mechanism without case and dial.

A portion of the drive mechanism of the Van Sicklen tachometer is indicated by A in Fig. 1 and also in Fig. 2. A in Fig. 2 is the driving tang which is connected to the rotating shaft which speed is to be measured. A is a worm fixed to the upper end of A, and B rotates on a stud in a sleeve which is forced into the threaded hole of the tachometer case. A ball thrust bearing takes care of the end thrust caused by the action of the worm while a phosphor bronze sleeve serves as a guide bearing.

Part C (Fig. 2) remains of two gears mounted on a pivoted plate one of which has a crimped spring washer under it to



FIG. 2. DRIVING MECHANISM ASSEMBLED BY BOTTOM PLATE

reverse rotation, as A turns, parts C rotate from through the mechanism of the other end B. A clockwise rotation of B causes the pivoted plate C to turn in an anti-clockwise direction. On the front of the target required to measure the distance that action causes the right hand gear of C, to throw into mesh with lower gear of the spring barrel and shown in Fig. 3, which results in ball bearing B (Fig. 2).

Should there be a complete rotation of pinion of driving tang A (Fig. 2) with a consequent reversal of B the pivoted



FIG. 3. POWER PLATE

plate C would turn in clockwise direction and throw the left hand gear of C into mesh with lower gear of the spring barrel said. It will be seen that through the action of reverse said C (Fig. 2), the gear A in Fig. 3 will rotate in the same direction the driving tang. D is the spring barrel and contains a coiled mass spring similar to that of a watch.

In Fig. 1 gear A is fast to shaft E and as gear C the spring is followed in the shaft, while the outer end bears against a polished ring, the whole assembly being fixed with special grease. As the shaft E rotates, it winds up the spring until the longer gear causes the friction between the end of the spring and the polished ring, and then the end of the spring starts to slip. The spring is therefore kept wound up to maintain tension by power.

The spring barrel *B* furnishes the power for driving the watch and *C* (Fig. 1), through gear *F* and intermediate gearing, just as in an ordinary watch. The complete watch mechanism is shown in Fig. 2 as a temperature compensated balance and through escape mechanism similar to that used on regular watches allows the fly *E*, which has two arms, to swing a pointer *c* every half second. The frame, disc *D*, rotates by friction with *E* and is used as a shock absorber to prevent injury to the watch mechanism and also to the wing web release.

GOING *A* (Fig. 4) turns with fly *E* and through intermediate gearing allows spring barrel *B* (Fig. 1) to unwind through a drum on every half second. Cass *B* (Fig. 3) are fixed to spring barrel and turn with it every half second.

By referring to Fig. 1 it will be seen that the gear actuated by motor screw *B* is in mesh with the top gear of the spring

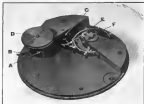


FIG. 4. WATCH MECHANISM

barrel shaft. Directly under this gear and fastened to it is a small V-tooth gear. This gear meshes at a speed which is directly proportional to that of the driving lary since it is connected through a train of gears, this gear is mounted on a lever which is actuated by a spring. The lower end of the lever leans against the middle cam Fig. 3 which causes it to rise and fall alternately.

When the lever is down the small V-tooth gear is in mesh with the counter gear Fig. 3, called the counting gear. The screw race allows the watch gear to be in mesh for exactly one second during which time the counting gear is turned at a rate proportional to the speed of the drive. At the end of one second the small gear is thrown out of mesh for one second then it is allowed to be thrown into mesh again, so that the counting gear gives a new counting of speed every alternate second.

In Fig. 3 *C* is a counting gear with stop gear *F* which engages a fulcrum *M* free to turn about the center of the axis. This arm in turn engages stop pin *O* as a variable gear so that as the counting gear turns the rubber gear *E* is turned also. *E* is fastened to the motor shaft which carries the pointer.

A locking lever which holds the rubber gear in place is lifted for a short interval by the lower arm *E* (Fig. 3), once during each cycle of operation. During a complete cycle of operation involving four movements of the fly or a period of two seconds, the following actions take place: The small gear is thrown into mesh with the counting gear for one second, the pointer is brought up to a position which indicates the average speed obtained; the small gear is then thrown out of mesh and at the same time a locking lever drops into place and holds the counting gear in its advanced position, at the same time the rubber lever or the rubber gear is released so that the lever can drop back through the action of the spring to engage release speed. If there should be a reduction in speed between the release of holding the rubber gear and the spring locking the counting gear it is then released by the action of the top cam, Fig. 3, and a spring returns the counting gear to its

zero point. During the next cycle the counting gear gives a new count of speed and the hand is allowed to accommodate itself to the new position and to hold it while the counting gear returns for the next cycle. The hand of the instrument is accordingly reset every two seconds and requires average speed error not exceed.

It may be seen from an analysis of these operations that the instrument is strictly mechanical in its principle and that its calibration is controlled by the timing of the watch. In the



FIG. 5. COUNTING MECHANISM

Two similar instruments the watch used is unaffected by two pressure variations as great as its compensated balance. The following results were obtained by the Bureau of Standards at Washington, D. C., upon the average of all of the production samples submitted:

The maximum calibration error based on a full scale reading, was about 3 of 1 per cent. The change caused by 500 ft. of vibration and jarring was about 1 of 1 per cent, while the greatest temperature error, range of temperature from -20 deg. Cent. to +10 deg. Cent. was a little over 1 of 1 per cent. Inasmuch as this instrument is available to the nearest 20 p.p.m. it will be seen that the accuracy is less than the smallest drum it then can be read on the tachometer.

New Passenger Zeppelin

A new Zeppelin airship, named *Rohdenn*, on its maiden trip from Friedrichshafen, Berlin, attained a maximum speed of 75 miles an hour.

The builders of the new type of machine have described the fuselage, outer shape of the old Zeppelin and adapted a streamline hull shape.

The *Rohdenn* is 120 meters long and accommodates thirty passengers. It is equipped with wireless telegraphy, also has a spacious passenger cabin. The passengers are able to obtain running hot and cold water. The airship is to go into daily service.

British Seek Mail Data

That the American airmail mail service is attracting international attention is indicated by the receipt of a letter from Winston Spencer Churchill, British Air Minister, to John A. Jordan, representative of the Cleveland-Chicago air mail division, in which he seeks all possible data on the system. The letter has been forwarded to Washington.

Mr. Churchill's letters bear down on British air systems and says that Britain is seeking every possible method to improve and develop airmail travel.

New Air Routes

The Curtiss Aeroplane and Motor Corp. has announced plans for three air routes for passenger service. They will be to Rochester, Syracuse, Utica and Albany, to Erie and Pittsburgh, Pa., and across the Canadian border to Boston and Toronto. The route north will be opened this fall, but the other two possible will not be in operation until spring.

Prediction of Airplane Performance

By I. M. Laddin

Aeronautical Engineer, U. S. Air Service

The following method of estimating airplane performance was outlined to the author by Lieutenant Allen of the French Aviation Mission. It consists in comparing the airplane whose performance is to be found with the actual performance of an airplane of similar type on a power and a surface loading basis.

The actual performances of three different types of airplanes are given on the chart. These airplanes are all good, clean

Examples—Two engine airplane, weight, 7200 lbs.; horsepower, 360; surface, 900 sq. ft.

The engine plane to use for comparison is the two-engine plane.

1. Find the information on reference line *B* of a straight line through the propeller efficiency and horsepower.

2. Join this point to the surface and note the intersection on line *F*.

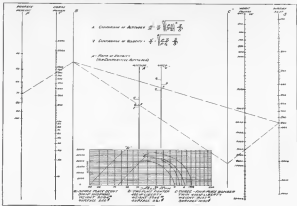


CHART FOR ESTIMATING AIRPLANE PERFORMANCE

designs, therefore, when comparing an airplane that is poor aerodynamically with any one of the above, an allowance should be made in the high speed obtained. In extreme cases this allowance may run as high as 20 mph., but for all ordinary designs no allowance need be made. The scaling is and correspondingly affected. Curves of actual performance shown include the three common types: (a) Single-plane scout. (b) Two-plane fighter or reconnaissance airplane. (c) Three or four-plane, two-engine bomber. By selecting the proper type for comparison one can make an accurate prediction.

It has been the author's experience that the results obtained through this simple method are much more reliable than those given by the old laborious method of computing the parasite resistance, horsepower required, weight, etc. It should prove quite useful to the designer, since it affords a rapid and accurate means of estimating how changes in weight, surface or horsepower affect the performance of the plane in question.

3. Find the information on reference line *F* on a straight line through weight and surface.

4. Join point on reference line *F* to point on reference line *B*, and note intersection on line *A*.

The linear difference between the points found on lines *A* and *F* and the corresponding points given for the plane which it is being compared with are the measures of the relative engine and speed.

5. Construct a curve similar to curve *C*, using ordinates increased (or decreased) by the difference in altitude (*C* and *C'*) and also increased (or decreased) by the difference in speed (*C* and *C'*).

6. From the point of absolute scaling (*B*) draw curve parallel to curve *C*. This curve gives the maximum speed for horizontal flight at given altitude, while the curve first constructed gives the high speed. The enclosed area is the speed range.

Reducing Shrinkage and Swelling in Laminated Wood Construction

By J. S. Mathewson

Engineer in Forest Products, U. S. Forest Products Laboratory

One of the results of the enormous and unexpended demand upon our timber resources during the war was the development of new methods of obtaining more efficiently the available supply of timber. One of the developments was the use of solid pieces of wood glued together and then machined or milled to any form. It is the purpose of this article to discuss briefly a number of the more important factors which relate to the wood itself and upon which the satisfactory use of wood in laminated construction largely depends. Gluing is not considered. It may be stated incidentally, however, that extensive experiments on the gluing of various species have been made at the Forest Products Laboratory of the U. S. Forest Service at Madison, Wis., and have afforded information which has been used as a basis for formulating specifications for the successful use of glue.

Before the stresses in laminated construction, such as an airplane propeller, strut or wing boom, are due to external forces, other stresses, called internal stresses, exist which are due to forces acting between or within the laminations. In some cases they may be of sufficient magnitude to cause serious swelling, and may independently, or in combination with stresses due to external force, result in failure of the structural member. The great importance of this fact is indicated by the very large percentage of propellers which have been rejected as a result of the effect of internal stresses.

Some Shrinkage Characteristics of Wood

If a stick of green timber is dried gradually it will retain the same dimensions until the moisture content of some part of it reaches the fiber saturation point, which for most species corresponds to a moisture content of between 20 and 30 per cent, based on the oven-dry weight of the wood. As the drying continues below this point, however, the moisture begins to leave the cell walls and shrinkage occurs.

Investigation has shown that the most apparent shrinkage around the tree, or in a longitudinal direction, is much greater than that from the center toward the circumference, or in a radial direction. The width of a piece or flat-sawn board is in the circumferential direction, while that of a quarter-sawn board is in the radial direction. Thus shrinkage in moisture content, the shrinkage in the width of a quarter-sawn board averages about 0.6 as great as that of a flat-sawn. In general, the shrinkage parallel to the axis of the tree is negligible.

Shrinkage is closely related to the density of wood; dry wood when exposed to very moist air absorbs moisture and swells. Conversely, wood dried to practically constant moisture in a relatively dry climate, if exposed to unexpectedly dry conditions loses more moisture and shrinks. Two pieces of wood of a given species when exposed continuously to the same conditions of temperature and humidity will shrink some 10 per cent less (width about 1 per cent) moisture content, irrespective of their relative moisture contents when first exposed to such conditions.

Quarter-sawn and plane-sawn boards differ in their rate of drying, and even embedded pieces cut from a tree in the same manner differ in this respect. Not only do dense pieces shrink more than light pieces, but they also dry more slowly. Position in the pile on any seasoning or in a kiln or drying chamber, of course, has a large influence on rate of drying.

Possible Effect of Shrinkage on Laminated Construction

Suppose a flat-sawn board be glued between two quarter-sawn boards, all being dried and subsequent to drying, subsequent changes of moisture content, the flat-sawn board will, as noted above, tend to shrink or swell more than the quarter-sawn boards. This difference will set up a shrinking stress in the glued joint. As a result the glued joint may give way entirely, it may partially fail, or it may hold perfectly. In either of the latter cases the weaker piece will be under stress in tension when the greater, corresponding, external tendency to split. This tendency may become increased and

result in a weakening of the wood fibers, the effect of which may be made to resemble. From these considerations it is evident that better results would be secured by having all the laminations either quarter-sawn or plane-sawn, so that the difference between the shrinkages of adjacent laminations would be reduced to a minimum. In general, and better results would be obtained by the use of quarter-sawn boards, even if they shrink considerably less than flat-sawn boards, quarter-sawn boards also dry less rapidly. This characteristic would tend to cause additional shrinkage in a glued joint between quarter-sawn and flat-sawn laminations.

Again, if the several laminations differ in moisture content or in density these factors may affect to a marked degree the relative shrinkage of the laminations, and consequently the strength of the glued joint.

It is possible, moreover, that the conditions cited in the two preceding paragraphs may tend to complicate and further emphasize the difficulty of securing satisfactory construction. For instance, suppose that a propeller consists of alternate laminations of flat-sawn, quite dense boards at a relatively high moisture content glued up with boards which are quarter-sawn, less dense, and in a much lower moisture content when glued. The tendency of the flat-sawn laminations to shrink or swell with subsequent changes of moisture content will be very much greater than that of the others, with the result that internal stresses of considerable magnitude will be developed. It is apparent, therefore, that these internal stresses may combine with the stresses from external causes to produce failure under smaller external load than would be the case if more care were taken during the manufacturing process.

Moisture Content Same as in Sample

It is very desirable not only to have the moisture content of the individual laminations the same at the time of gluing, but also to have it approximately that to which it will ultimately reach in use. For example, a propeller to be used in a hot, dry climate, such as that of the Mexican border, should be constructed of laminations having a lower moisture content than can be used in a more humid climate such as that of England.

Time for the Manufacturer

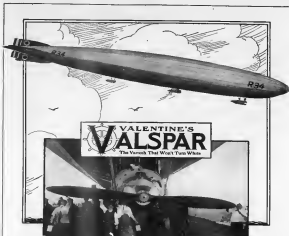
It is worth while now to consider how the manufacturer can satisfy some of the conditions necessary for successful construction involving laminated construction.

Quarter-sawn material usually includes boards in which the edge made with the radial surface by the annual growth rings (or shows in a cross section) is 45 deg. or more. In case the manufacturer's stock consists of mixed flat-sawn and quarter-sawn boards, an improvement will be made if these boards are dried into three groups—quarter-sawn, flat-sawn and quarter-sawn. A structural member could then be made entirely from boards of one group, which would minimize any source of shrinkage. Further, a slightly better result would be obtained by grouping according to their densities in advance in order to prevent the use of boards in the same member if they differ considerably in density.

In order to shrink as far as may be possible, troubles arising from differences in moisture content, it is very desirable that after the boards have been dried they be stored under proper conditions of temperature and humidity for a sufficient length of time to permit them all to come to the same moisture content before gluing. This will minimize the moisture stresses in the glue joints.

As additional storage after gluing and before the first reaching-out is advantageous so that it allows the moisture introduced with the glue to be uniformly distributed throughout the board.

In many cases the deleterious effect of internal stresses may be minimized by using quarter-sawn material glued according to density or dry weight and having a moisture content approximately that to which it will eventually come in service.



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